

10/533265

WO 2004/059830

1/19

PCT/EP2003/014211

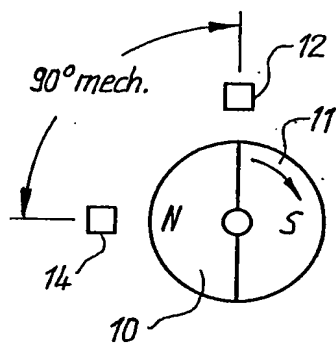


Fig. 1

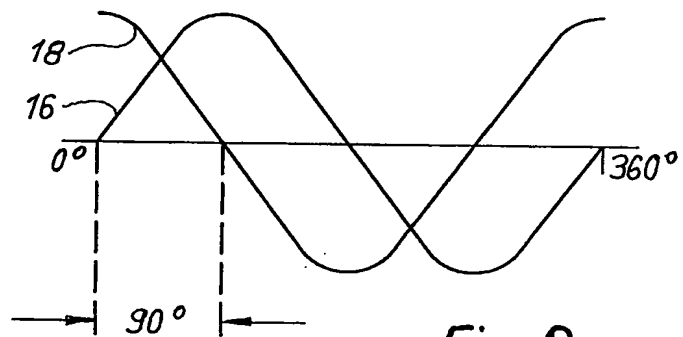


Fig. 2

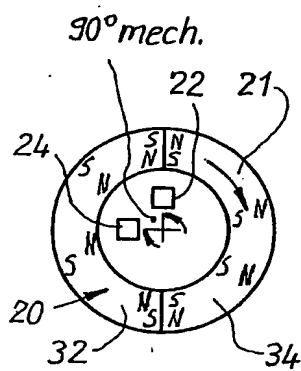


Fig. 3

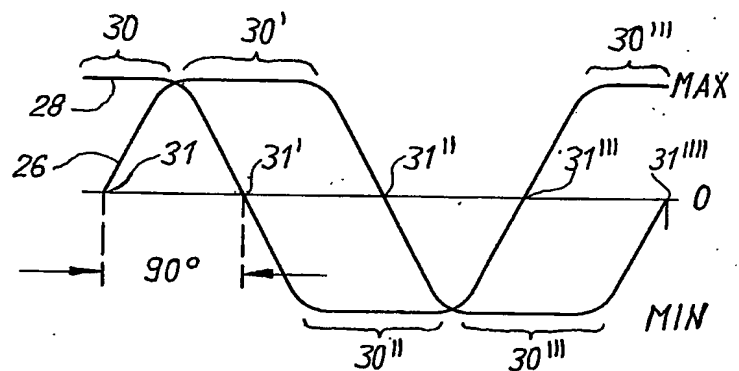


Fig. 4

10/533265

WO 2004/059830

2/19

PCT/EP2003/014211

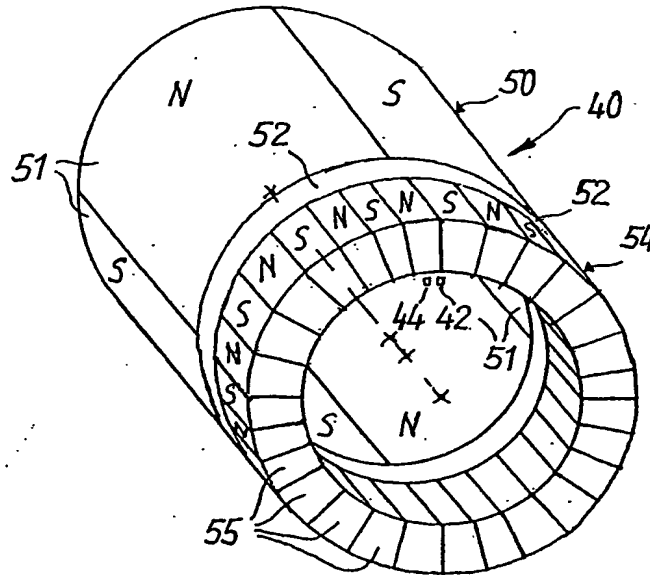
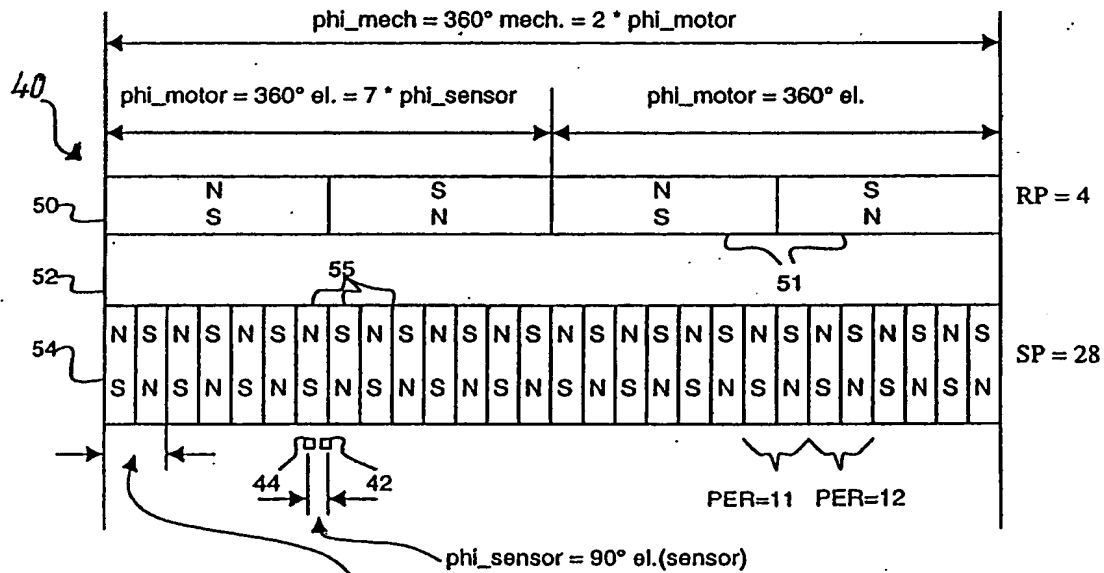


Fig. 5



$\phi_{\text{sensor}} = 360^\circ \text{ el. (sensor)}$
 $\phi_{\text{motor}} = 360^\circ \text{ el.} / 7 = 51,43^\circ \text{ el.}$
 $\phi_{\text{mech}} = 360^\circ \text{ mech.} / 14 = 25,71^\circ \text{ mech.}$

Fig. 6

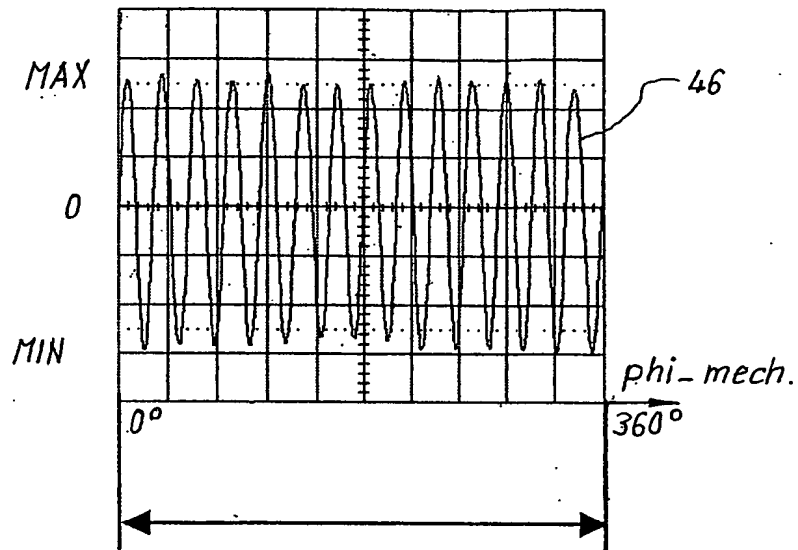


Fig. 7

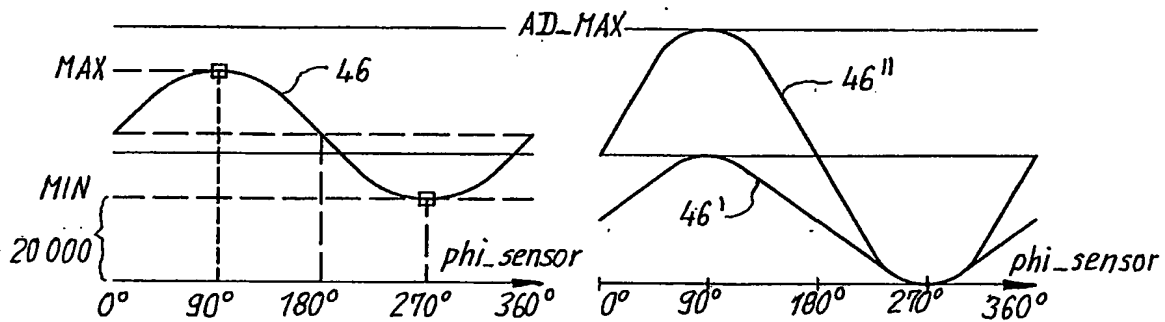


Fig. 8

Fig. 9

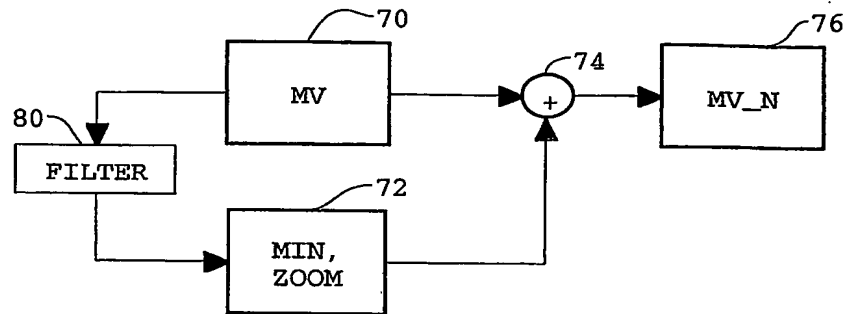


Fig. 10

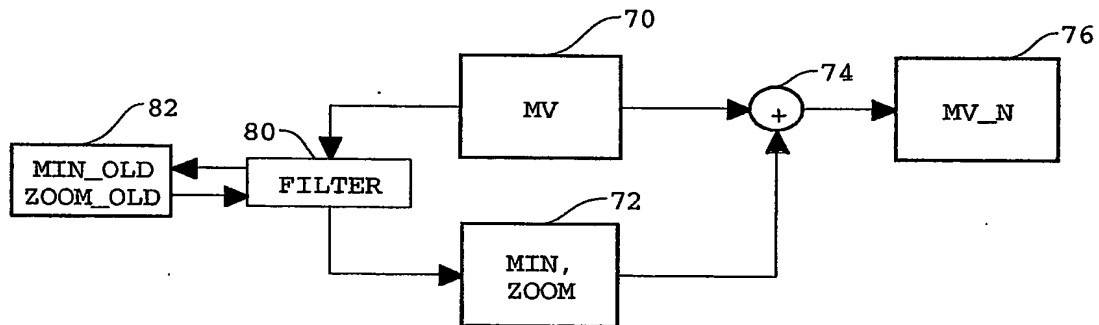


Fig. 11

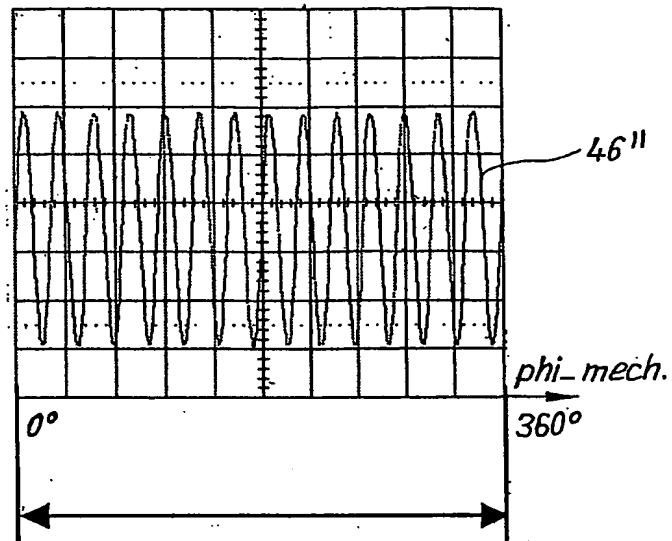


Fig. 12

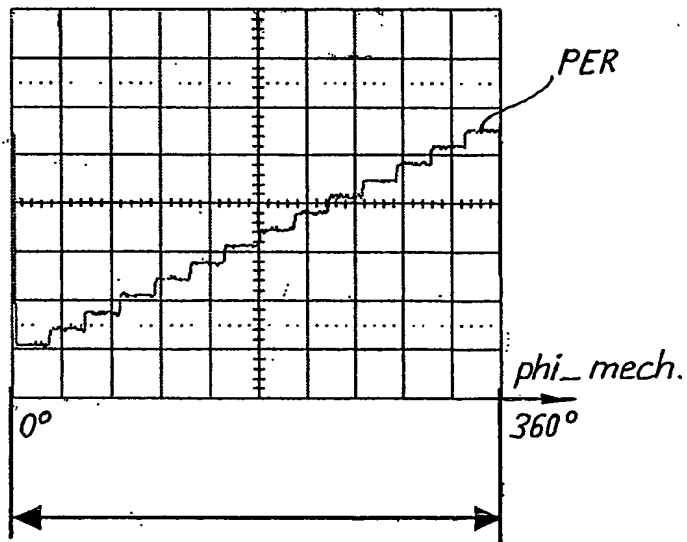


Fig. 13

10/533265

WO 2004/059830

6/19

PCT/EP2003/014211

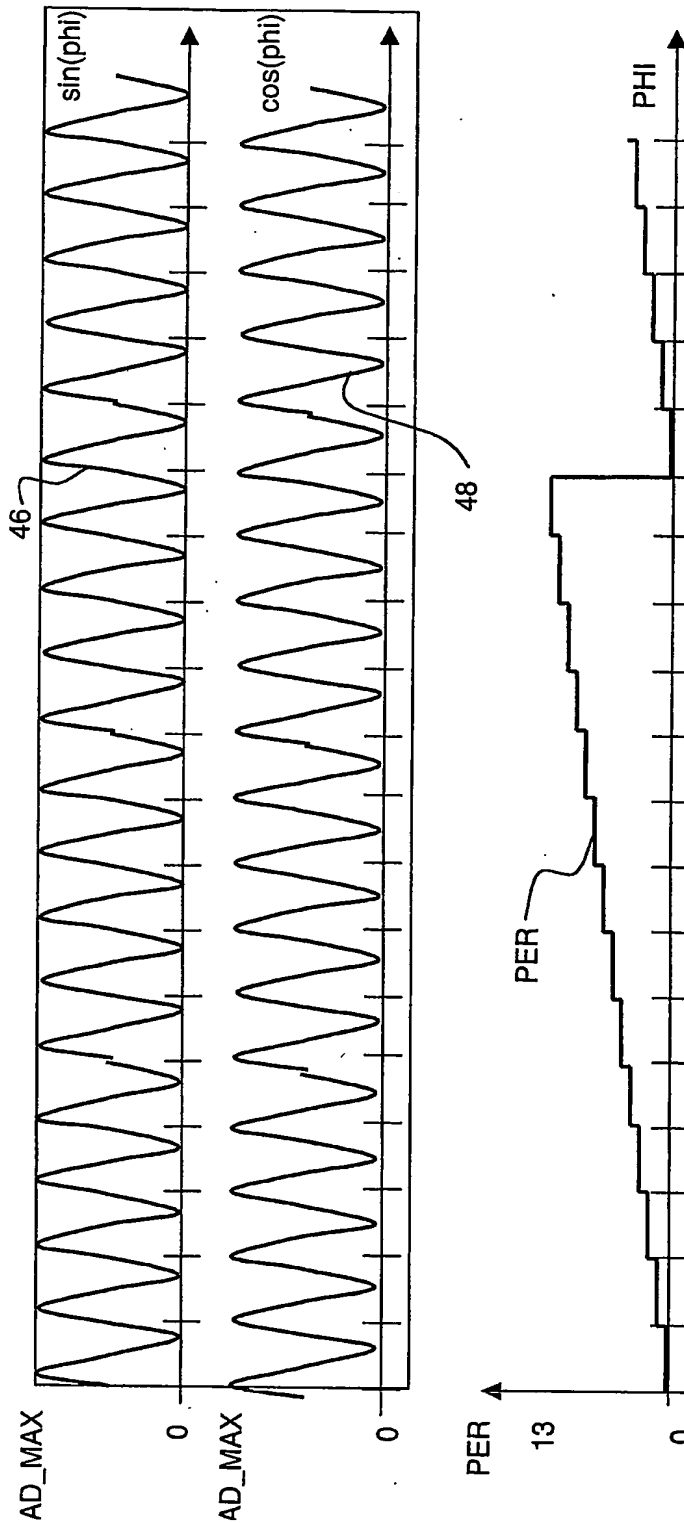


Fig. 14

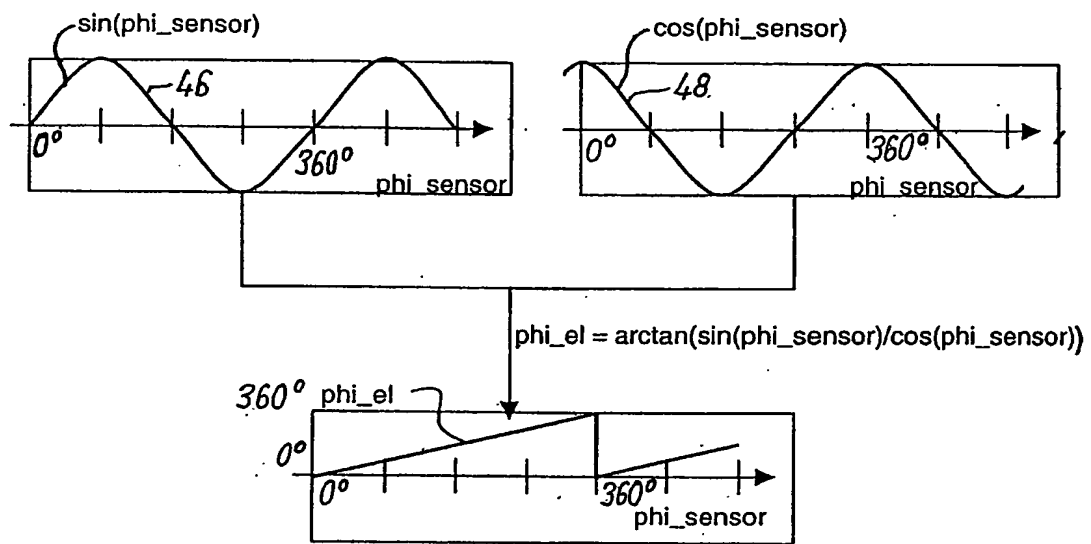


Fig. 15

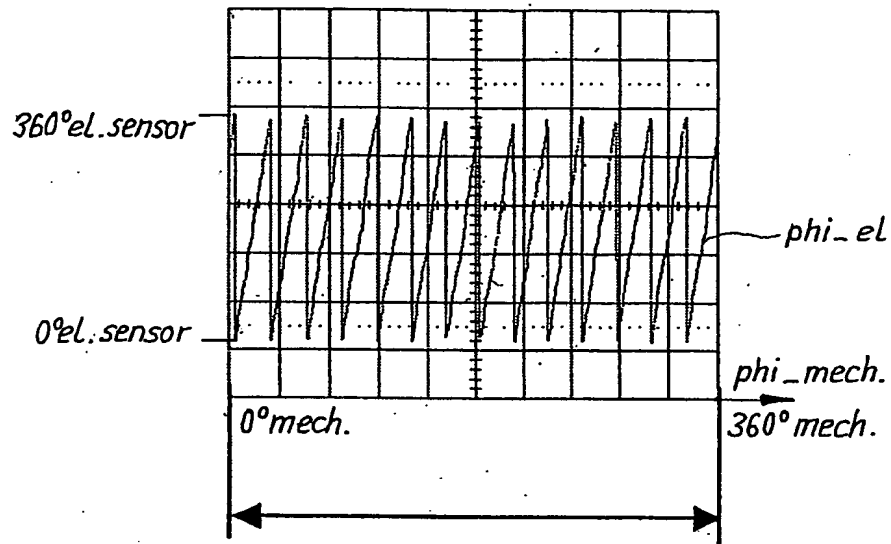


Fig. 16

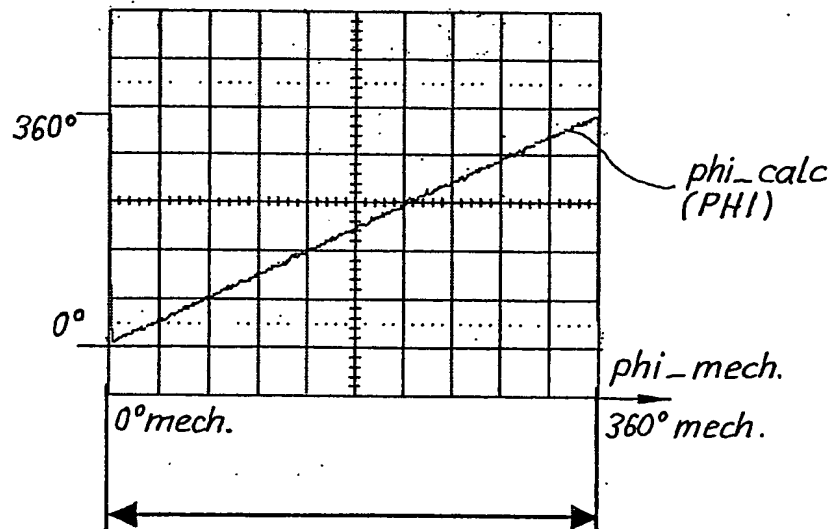
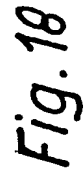


Fig. 17



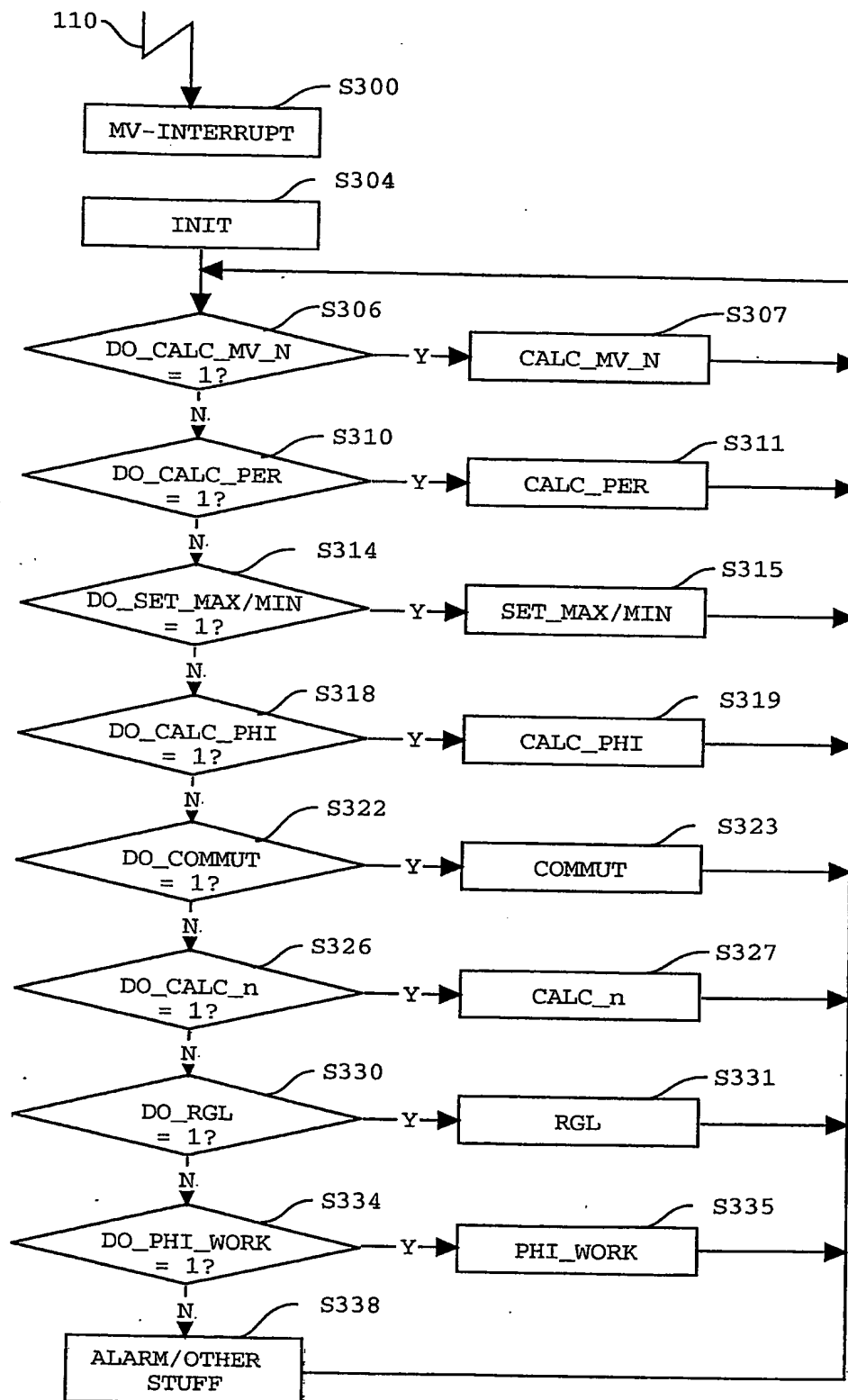


Fig. 19

10/533265

WO 2004/059830

PCT/EP2003/014211

11/19

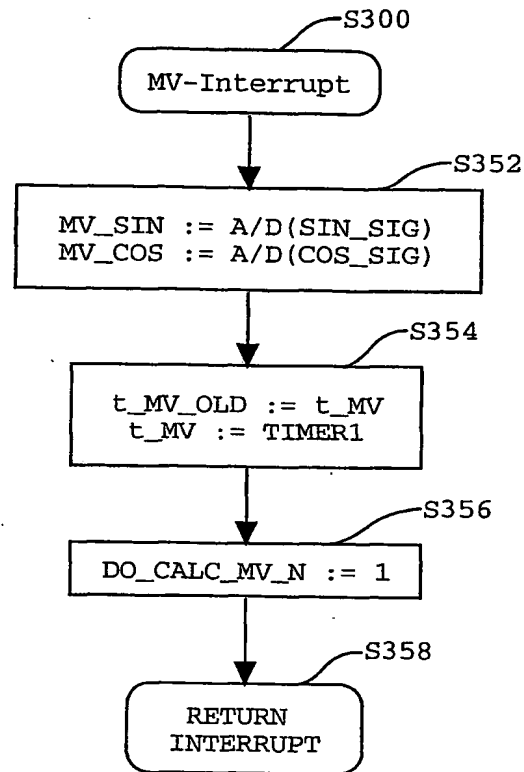


Fig. 20

10/533265

WO 2004/059830

12/19

PCT/EP2003/014211

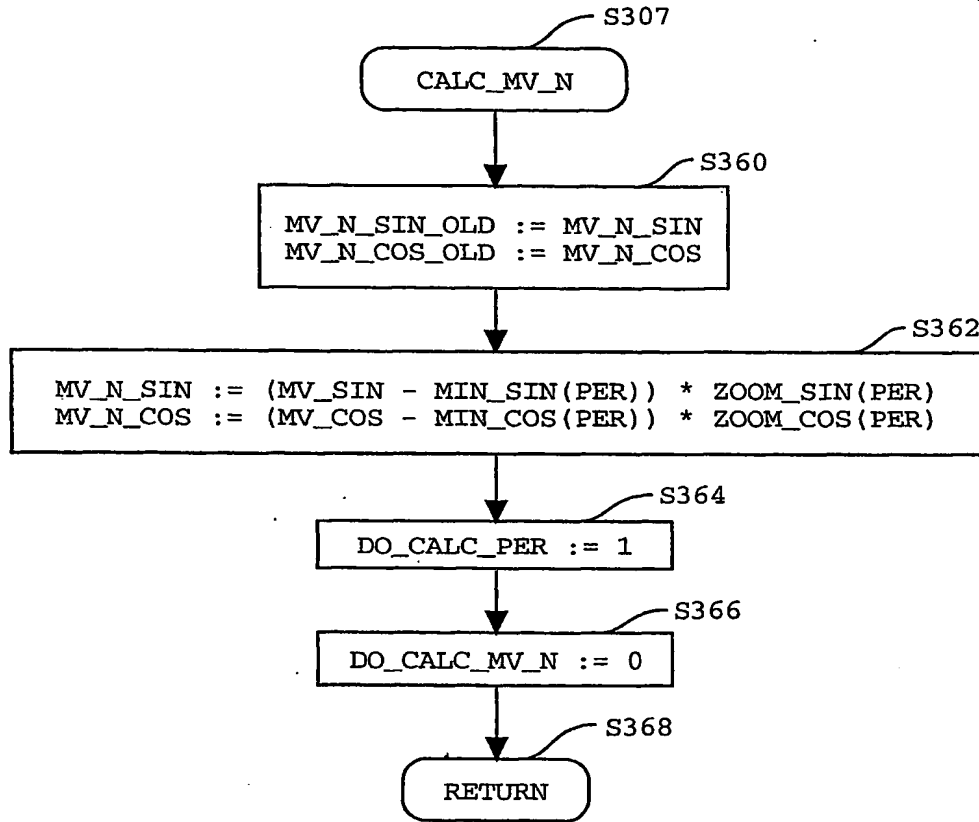


Fig. 21

10/533265

WO 2004/059830

13/19

PCT/EP2003/014211

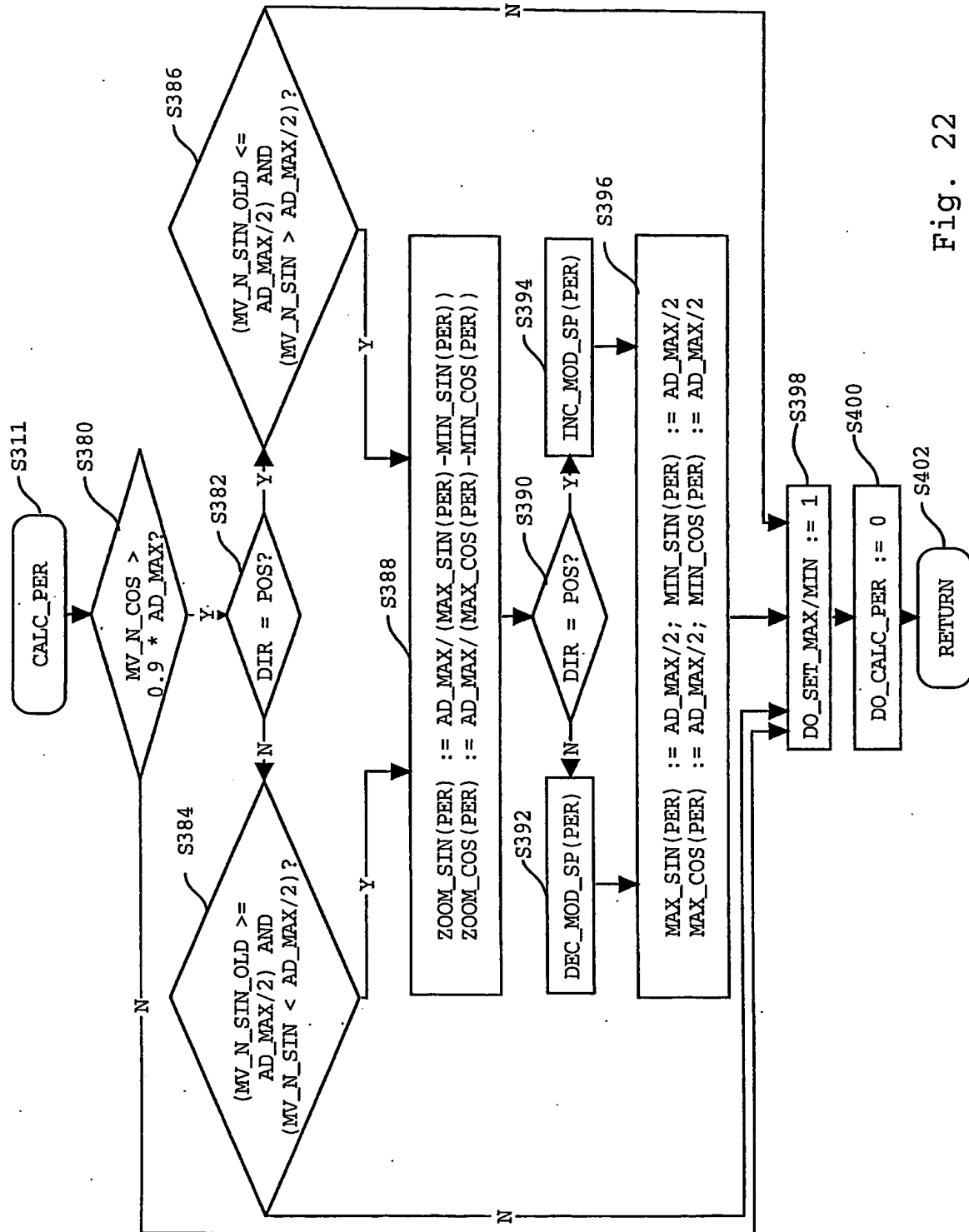


Fig. 22

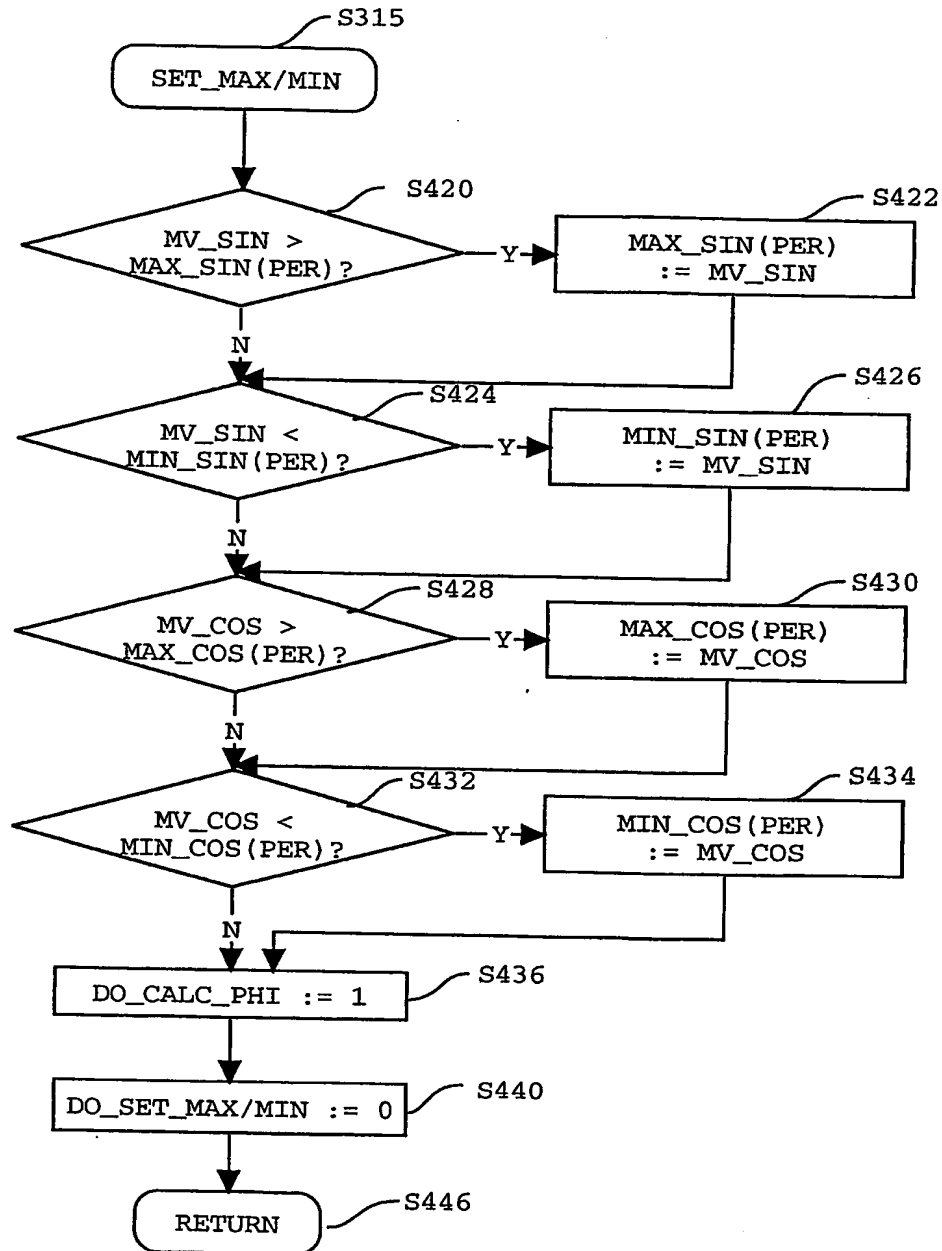


Fig. 23

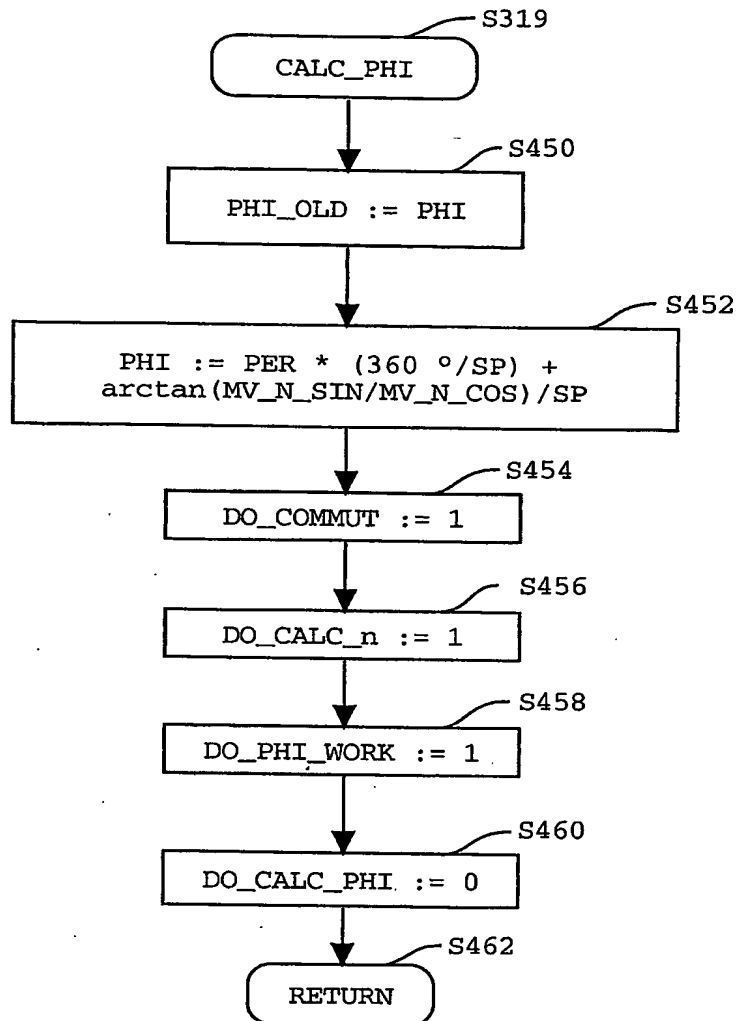


Fig. 24

10/533265

WO 2004/059830

16/19

PCT/EP2003/014211

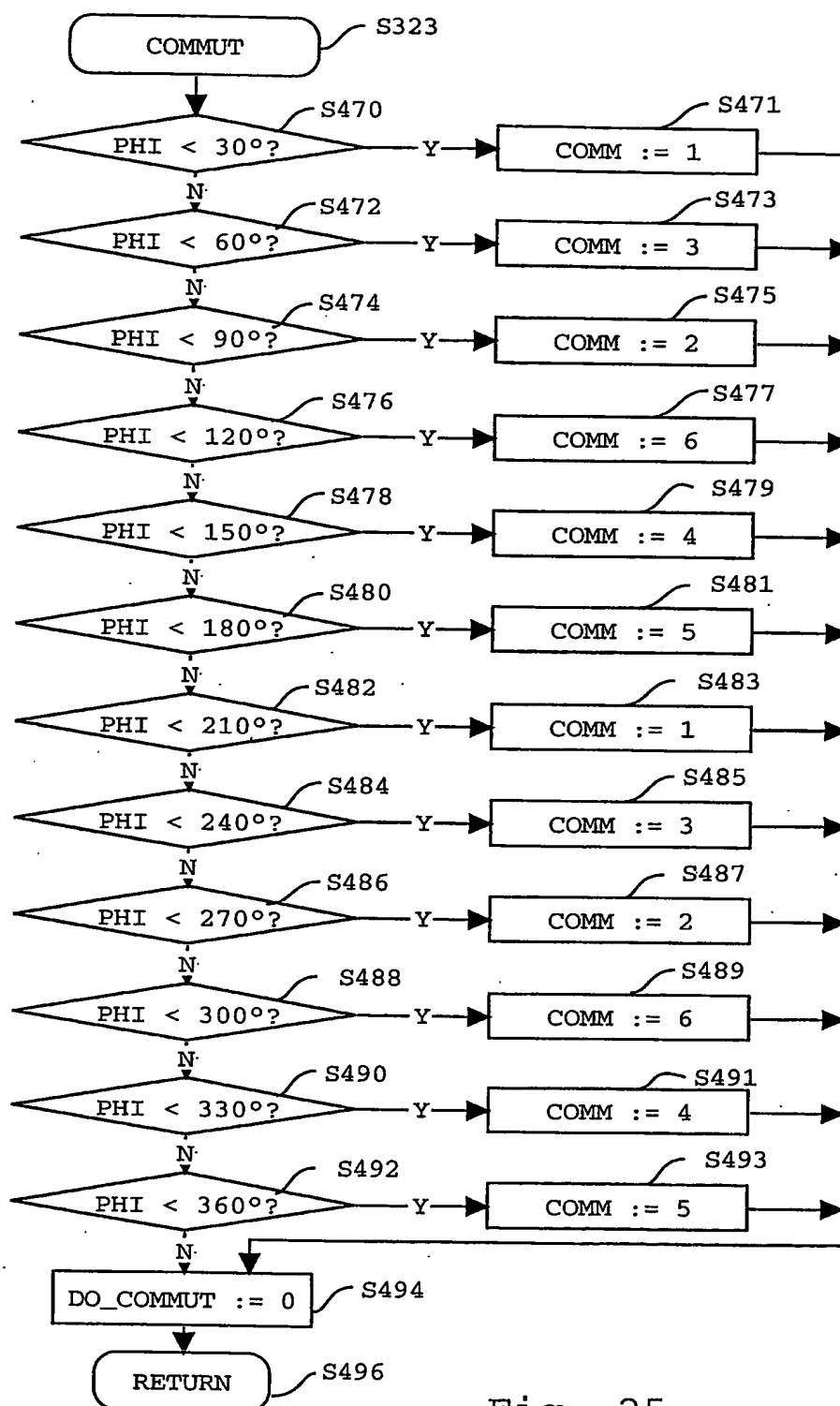


Fig. 25

10/533265

WO 2004/059830

17/19

PCT/EP2003/014211

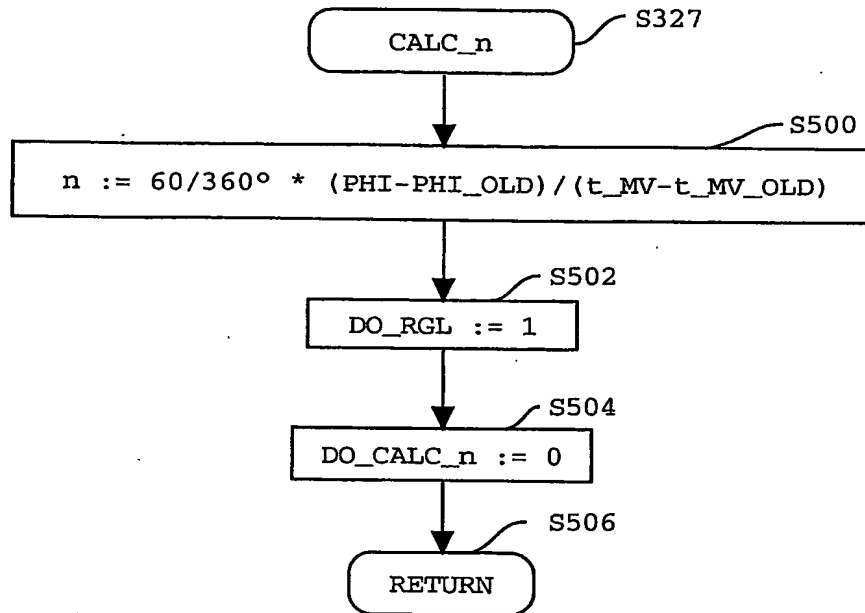


Fig. 26

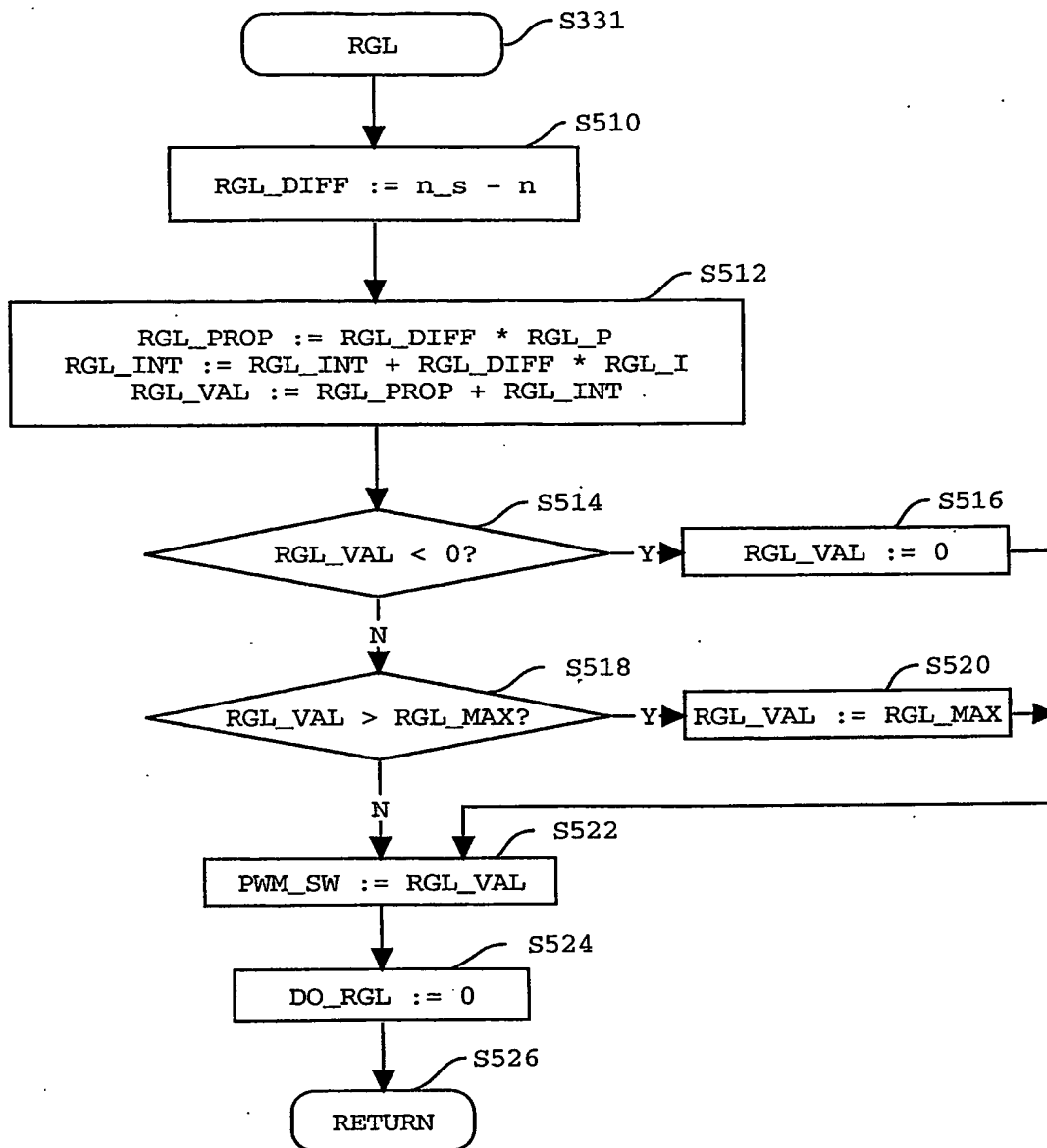


Fig. 27

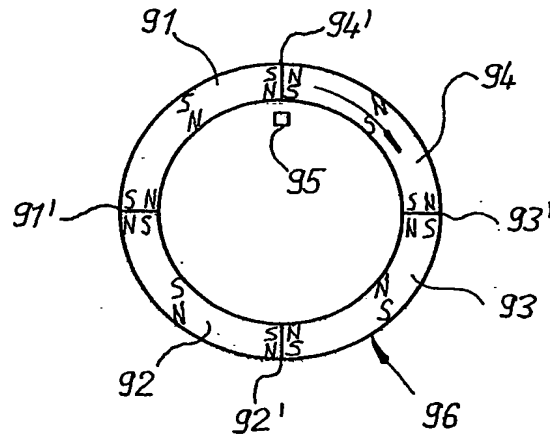


Fig. 28

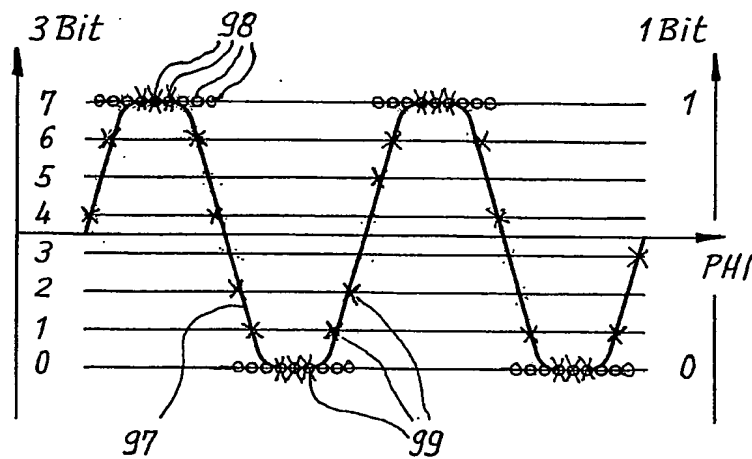


Fig. 29